

7.3 Constrained Optimization

Example (Typical problem)

Consider the quadratic form:

$$Q(x_1, x_2, x_3) = 3x_1^2 + 3x_2^2 + 4x_3^2 + 4x_1x_2 + x_1x_3 + x_2x_3$$

Find the maximum value of Q Subject to the

Constraint $\|\vec{x}\| = 1$.

Ans:

$$Q(\vec{x}) = \vec{x}^T A \vec{x}$$

Where $A = \begin{bmatrix} 3 & 2 & 1 \\ 2 & 3 & 1 \\ 1 & 1 & 4 \end{bmatrix}$

Since A is Symmetric, it is orthogonally diagonalizable

It can be easily proved that

Eigenvalues of A : $\lambda_1 = 6, \lambda_2 = 3, \lambda_3 = 1$

Eigenvectors of A : $\vec{u}_1 = \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}, \vec{u}_2 = \quad \vec{u}_3 =$

Using the ppal axes theorem $Q(\vec{x})$ can be transformed into a quadratic form with no cross-product terms.

If $\vec{x} = P\vec{y}$, where $P = [\hat{u}_1, \hat{u}_2, \hat{u}_3]$

$\hat{u}_1, \hat{u}_2, \hat{u}_3$ are the corresponding ^{normalized} eigenvectors for $\lambda_1, \lambda_2, \lambda_3$.

$$Q(\vec{x}) = \vec{x}^T A \vec{x} = (P\vec{y})^T A (P\vec{y}) = \vec{y}^T (P^T A P) \vec{y}$$

$$\stackrel{A \text{ Symm.}}{=} \vec{y}^T D \vec{y} = Q(\vec{y})$$

Where $D = \begin{bmatrix} \lambda_1 & 0 & 0 \\ 0 & \lambda_2 & 0 \\ 0 & 0 & \lambda_3 \end{bmatrix} = \begin{bmatrix} 6 & 0 & 0 \\ 0 & 3 & 0 \\ 0 & 0 & 1 \end{bmatrix}$

It means Q in the new variables y_1, y_2, y_3 transforms into

$$Q(y_1, y_2, y_3) = 6y_1^2 + 3y_2^2 + y_3^2.$$

Obviously,

$$Q(\vec{y}) = 6y_1^2 + 3y_2^2 + y_3^2 \leq 6y_1^2 + 6y_2^2 + 6y_3^2 \leq 6(y_1^2 + y_2^2 + y_3^2)$$

If $\|\vec{y}\| = 1 \Rightarrow \underline{\underline{Q(\vec{y}) \leq 6}}$ for all $\vec{y}$ s.t. $\|\vec{y}\| = 1$.

Also, if $\|\vec{y}\|=1$

$$Q(\vec{y}) = 6y_1^2 + 3y_2^2 + y_3^2 \geq y_1^2 + y_2^2 + y_3^2 = 1$$

So $\boxed{Q(\vec{y}) \geq 1}$ for $\|\vec{y}\|=1$

Since $Q(1,0,0) = 6$ $\begin{matrix} \vec{y} \\ \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} \end{matrix} \xrightarrow{P} \begin{matrix} \vec{x} \\ \begin{bmatrix} 1/\sqrt{6} \\ 1/\sqrt{3} \\ 1/\sqrt{3} \end{bmatrix} \end{matrix}$ Eigenvector of $\lambda_1 = 6$.

The maximum is reached when $\vec{y} = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$

Similarly,

minimum $\boxed{Q(0,0,1) = 1}$

Theorem 6 (Boor).